

# Topics in Monge-Ampère type Equations III

Cristian E. Gutiérrez

Temple University, Philadelphia, PA

Segovia Conference  
Buenos Aires, December 2005

I

# INTRODUCTION

# OPTIMAL TRANSPORTATION PROBLEM

# OPTIMAL TRANSPORTATION PROBLEM

- $\Omega_1, \Omega_2 \subset \mathbb{R}^n$  domains such that  $|\Omega_1| = |\Omega_2|$

# OPTIMAL TRANSPORTATION PROBLEM

- $\Omega_1, \Omega_2 \subset \mathbb{R}^n$  domains such that  $|\Omega_1| = |\Omega_2|$

- A cost function is given:

$c(x, y) =$  cost of transporting a unit from  $x \in \Omega_1$  to  $y \in \Omega_2$

# OPTIMAL TRANSPORTATION PROBLEM

- $\Omega_1, \Omega_2 \subset \mathbb{R}^n$  domains such that  $|\Omega_1| = |\Omega_2|$
- A cost function is given:  
 $c(x, y) =$  cost of transporting a unit from  $x \in \Omega_1$  to  $y \in \Omega_2$
- Find a measure preserving map  $t : \Omega_1 \rightarrow \Omega_2$ , i.e.,  $|t^{-1}(E)| = |E|$  for each  $E \subset \Omega_2$  such that minimizes the total cost

$$\int_{\Omega_1} c(x, t(x)) dx$$

# BASIC QUESTIONS

## BASIC QUESTIONS

- Existence and uniqueness of solutions

## BASIC QUESTIONS

- Existence and uniqueness of solutions
- What form the solutions have?

## BASIC QUESTIONS

- Existence and uniqueness of solutions
- What form the solutions have?
- Is this problem related to some pde?

## BASIC QUESTIONS

- Existence and uniqueness of solutions
- What form the solutions have?
- Is this problem related to some pde?
- How regular is the optimal map?

## HISTORY OF THE PROBLEM

- Monge (1781) formulated the problem for the first time,  $c(x, y) = |x - y|$

## HISTORY OF THE PROBLEM

- Monge (1781) formulated the problem for the first time,  $c(x, y) = |x - y|$
- Kantorovitch (1942) reformulated the problem in probabilistic terms, optimal maps  $\rightarrow$  optimal plans, can use linear programming. Formulation weaker than Monge.

## HISTORY OF THE PROBLEM

- Monge (1781) formulated the problem for the first time,  $c(x, y) = |x - y|$
- Kantorovitch (1942) reformulated the problem in probabilistic terms, optimal maps  $\rightarrow$  optimal plans, can use linear programming. Formulation weaker than Monge.

$X, Y$  compact metric spaces,  $\mu, \nu$  Borel measures on  $X$  and  $Y$  respectively with  $\mu(X) = \nu(Y)$ .

Let  $\Sigma$  be the class of Borel measures  $\sigma$  on  $X \times Y$  such that  $\sigma(E \times Y) = \mu(E) \forall$  Borel sets  $E \subset X$  and  $\sigma(X \times E') = \nu(E') \forall$  Borel sets  $E' \subset Y$ .

Consider

$$W(\sigma, \mu, \nu) = \iint_{X \times Y} c(x, y) d\sigma(x, y).$$

Kantorovitch's formulation is to find a measure  $\sigma_0$  such that

$$W(\sigma_0, \mu, \nu) = \inf_{\sigma \in \Sigma} W(\sigma, \mu, \nu).$$

This measure exists and in general is not unique.

Consider

$$W(\sigma, \mu, \nu) = \iint_{X \times Y} c(x, y) d\sigma(x, y).$$

Kantorovitch's formulation is to find a measure  $\sigma_0$  such that

$$W(\sigma_0, \mu, \nu) = \inf_{\sigma \in \Sigma} W(\sigma, \mu, \nu).$$

This measure exists and in general is not unique.

- Kantorovitch, "The best use of economic resources". Methods to solve technical and economic problems such as:
  - the least wasteful allocation of work to machines,
  - the cutting of material with minimum loss,
  - the distributions of loads over several means of transport.

- Impressive number of applications and connections: Calculus of Variations, nonlinear pdes, Convex analysis, Probability, Economics, Statistical Mechanics, and other fields, see book by Rachev and Rüschendorf, Mass transportation problems, two volumes.

- Impressive number of applications and connections: Calculus of Variations, nonlinear pdes, Convex analysis, Probability, Economics, Statistical Mechanics, and other fields, see book by Rachev and Rüschendorf, Mass transportation problems, two volumes. Villani's recent book and John Urbas' lecture notes (1998).
- Kantorovitch and Koopmans received the Nobel prize in Economics in 1975, for "contributions to the theory of optimal allocation of resources".

## RECENT DEVELOPMENTS

- If  $c(x, y) = |x - y|^2/2$ , then the optimal map  $s = D\phi$  with  $\phi$  a convex function.

## RECENT DEVELOPMENTS

- If  $c(x, y) = |x - y|^2/2$ , then the optimal map  $s = D\phi$  with  $\phi$  a convex function.
- This connects optimal transportation with the Monge-Ampère equation: using his regularity theory for the M-A equation, Caffarelli obtained regularity of the optimal maps.

## RECENT DEVELOPMENTS

- If  $c(x, y) = |x - y|^2/2$ , then the optimal map  $s = D\phi$  with  $\phi$  a convex function.
- This connects optimal transportation with the Monge-Ampère equation: using his regularity theory for the M-A equation, Caffarelli obtained regularity of the optimal maps.
- For general cost functions we have the following result of Caffarelli, Gangbo and McCann (1996):

**Theorem.**  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  strictly convex,  $f, g \in L^1(\mathbb{R}^n)$  nonnegative with bounded support, and  $\int_{\mathbb{R}^n} f(x) dx = \int_{\mathbb{R}^n} g(y) dy$ .

**Theorem.**  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  strictly convex,  $f, g \in L^1(\mathbb{R}^n)$  nonnegative with bounded support, and  $\int_{\mathbb{R}^n} f(x) dx = \int_{\mathbb{R}^n} g(y) dy$ . Given  $s \in \mathcal{S}(f, g)$ , i.e.,  $\int_{s^{-1}(E)} f(x) dx = \int_E g(y) dy$  for each Borel set  $E \subset \mathbb{R}^n$ , let

$$\mathcal{C}(s) = \int_{\mathbb{R}^n} c(x - s(x)) f(x) dx.$$

**Theorem.**  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  strictly convex,  $f, g \in L^1(\mathbb{R}^n)$  nonnegative with bounded support, and  $\int_{\mathbb{R}^n} f(x) dx = \int_{\mathbb{R}^n} g(y) dy$ . Given  $s \in \mathcal{S}(f, g)$ , i.e.,  $\int_{s^{-1}(E)} f(x) dx = \int_E g(y) dy$  for each Borel set  $E \subset \mathbb{R}^n$ , let

$$\mathcal{C}(s) = \int_{\mathbb{R}^n} c(x - s(x)) f(x) dx.$$

Then

1.  $\exists$  unique  $t \in \mathcal{S}(f, g)$  1-to-1 such that  $\mathcal{C}(t) = \inf_{s \in \mathcal{S}(f, g)} \mathcal{C}(s)$ ;

**Theorem.**  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  strictly convex,  $f, g \in L^1(\mathbb{R}^n)$  nonnegative with bounded support, and  $\int_{\mathbb{R}^n} f(x) dx = \int_{\mathbb{R}^n} g(y) dy$ . Given  $s \in \mathcal{S}(f, g)$ , i.e.,  $\int_{s^{-1}(E)} f(x) dx = \int_E g(y) dy$  for each Borel set  $E \subset \mathbb{R}^n$ , let

$$\mathcal{C}(s) = \int_{\mathbb{R}^n} c(x - s(x)) f(x) dx.$$

Then

1.  $\exists$  unique  $t \in \mathcal{S}(f, g)$  1-to-1 such that  $\mathcal{C}(t) = \inf_{s \in \mathcal{S}(f, g)} \mathcal{C}(s)$ ;
2.  $\exists$  a  $c$ -convex function  $u$  such that

$$t(x) = x - (Dc)^{-1}(-Du(x)) \text{ a.e.}$$

## PROGRAM

- Understand Monge original problem for general cost functions from the point of view of pde.

## PROGRAM

- Understand Monge original problem for general cost functions from the point of view of pde.
- Study a notion of generalized solution in Aleksandrov sense.

## PROGRAM

- Understand Monge original problem for general cost functions from the point of view of pde.
- Study a notion of generalized solution in Aleksandrov sense.
- Solve the Dirichlet problem

## PROGRAM

- Understand Monge original problem for general cost functions from the point of view of pde.
- Study a notion of generalized solution in Aleksandrov sense.
- Solve the Dirichlet problem
- How solutions of this pde are related to the optimal map?

## PROGRAM

- Understand Monge original problem for general cost functions from the point of view of pde.
- Study a notion of generalized solution in Aleksandrov sense.
- Solve the Dirichlet problem
- How solutions of this pde are related to the optimal map?
- Regularity of generalized solutions?

## PROGRAM

- Understand Monge original problem for general cost functions from the point of view of pde.
- Study a notion of generalized solution in Aleksandrov sense.
- Solve the Dirichlet problem
- How solutions of this pde are related to the optimal map?
- Regularity of generalized solutions?

## $c$ -CONVEXITY

- $u : \Omega \rightarrow \mathbb{R} \cup \{+\infty\}$ , not identically  $+\infty$ , is  $c$ -convex in  $\Omega$  if there exists a set  $A \subset \mathbb{R}^n \times \mathbb{R}$  such that

$$u(x) = \sup_{(y,\lambda) \in A} [-c(x - y) - \lambda] \text{ for all } x \in \Omega.$$

## $c$ -CONVEXITY

- $u : \Omega \rightarrow \mathbb{R} \cup \{+\infty\}$ , not identically  $+\infty$ , is  $c$ -convex in  $\Omega$  if there exists a set  $A \subset \mathbb{R}^n \times \mathbb{R}$  such that

$$u(x) = \sup_{(y,\lambda) \in A} [-c(x-y) - \lambda] \text{ for all } x \in \Omega.$$

- If  $c(x) = \frac{1}{2}|x|^2$ , then  $u$  is  $c$ -convex if and only if the function  $u + \frac{1}{2}|x|^2$  is convex.

## $c$ -CONVEXITY

- $u : \Omega \rightarrow \mathbb{R} \cup \{+\infty\}$ , not identically  $+\infty$ , is  $c$ -convex in  $\Omega$  if there exists a set  $A \subset \mathbb{R}^n \times \mathbb{R}$  such that

$$u(x) = \sup_{(y,\lambda) \in A} [-c(x-y) - \lambda] \text{ for all } x \in \Omega.$$

- If  $c(x) = \frac{1}{2}|x|^2$ , then  $u$  is  $c$ -convex if and only if the function  $u + \frac{1}{2}|x|^2$  is convex.
- If  $u$  is locally bounded and  $c$ -convex, then  $u$  is Lipschitz.

## $c$ -CONVEXITY

- $u : \Omega \rightarrow \mathbb{R} \cup \{+\infty\}$ , not identically  $+\infty$ , is  $c$ -convex in  $\Omega$  if there exists a set  $A \subset \mathbb{R}^n \times \mathbb{R}$  such that

$$u(x) = \sup_{(y,\lambda) \in A} [-c(x-y) - \lambda] \text{ for all } x \in \Omega.$$

- If  $c(x) = \frac{1}{2}|x|^2$ , then  $u$  is  $c$ -convex if and only if the function  $u + \frac{1}{2}|x|^2$  is convex.
- If  $u$  is locally bounded and  $c$ -convex, then  $u$  is Lipschitz.
- $u$  convex  $\implies u$  is  $c$ -convex.

## $c$ -SUBDIFFERENTIAL

- Let  $u : \Omega \rightarrow \mathbb{R} \cup \{+\infty\}$ . The  $c$ -subdifferential  $\partial_c u(x)$  at  $x \in \Omega$  is defined by

$$\partial_c u(x) = \{p \in \mathbb{R}^n : u(z) \geq u(x) - c(z - p) + c(x - p), \forall z \in \Omega\}.$$

## $c$ -SUBDIFFERENTIAL

- Let  $u : \Omega \rightarrow \mathbb{R} \cup \{+\infty\}$ . The  $c$ -subdifferential  $\partial_c u(x)$  at  $x \in \Omega$  is defined by

$$\partial_c u(x) = \{p \in \mathbb{R}^n : u(z) \geq u(x) - c(z - p) + c(x - p), \forall z \in \Omega\}.$$

- If  $c(x) = \frac{1}{2}|x|^2$ , then  $p \in \partial_c u(x)$  if and only if  $p \in \partial(u + c)(x)$ , i.e.,  $\partial_c u(x) = \partial(u + c)(x)$  where  $\partial$  denotes the standard subdifferential.

## $c$ -SUBDIFFERENTIAL

- Let  $u : \Omega \rightarrow \mathbb{R} \cup \{+\infty\}$ . The  $c$ -subdifferential  $\partial_c u(x)$  at  $x \in \Omega$  is defined by

$$\partial_c u(x) = \{p \in \mathbb{R}^n : u(z) \geq u(x) - c(z - p) + c(x - p), \forall z \in \Omega\}.$$

- If  $c(x) = \frac{1}{2}|x|^2$ , then  $p \in \partial_c u(x)$  if and only if  $p \in \partial(u + c)(x)$ , i.e.,  $\partial_c u(x) = \partial(u + c)(x)$  where  $\partial$  denotes the standard subdifferential.

- If  $c \in C^1(\mathbb{R}^n)$  and strictly convex, and  $u$  is differentiable at  $x_0$ , then

$$\partial_c u(x_0) = \{x_0 - (Dc)^{-1}(-Du(x_0))\}.$$

## EXAMPLE

Let  $c \in C^2(\mathbb{R}^n)$  and strictly convex. Suppose  $u \in C^2(\Omega)$ .

## EXAMPLE

Let  $c \in C^2(\mathbb{R}^n)$  and strictly convex. Suppose  $u \in C^2(\Omega)$ .

Then  $u$  is  $c$ -convex if and only if

$$I + D^2c^* (-Du(x)) D^2u(x) \geq 0,$$

where  $c^*$  is the Legendre-Fenchel transform of  $c$

$$c^*(y) = \sup_{x \in \mathbb{R}^n} [x \cdot y - c(x)].$$

## EXAMPLE

Let  $c \in C^2(\mathbb{R}^n)$  and strictly convex. Suppose  $u \in C^2(\Omega)$ .

Then  $u$  is  $c$ -convex if and only if

$$I + D^2c^* (-Du(x)) D^2u(x) \geq 0,$$

where  $c^*$  is the Legendre-Fenchel transform of  $c$

$$c^*(y) = \sup_{x \in \mathbb{R}^n} [x \cdot y - c(x)].$$

The notions of  $c$ -subdifferential and  $c$ -convexity were introduced by Elster and Nehse (1974) and Dietrich (1988), and recently used by Gangbo and McCann.

IV

A MONGE-AMPÈRE TYPE MEASURE  
ASSOCIATED WITH  $c$

**Theorem.** *Let  $\Omega$  be an open set in  $\mathbb{R}^n$ . Let  $u : \Omega \rightarrow \mathbb{R} \cup \{+\infty\}$  be such that on any bounded open set  $U \Subset \Omega$ ,  $u$  is not identically  $+\infty$  and bounded from below. Then the Lebesgue measure of the set*

$$S = \{p \in \mathbb{R}^n : \text{there exist } x, y \in \Omega, x \neq y \text{ and } p \in \partial_c u(x) \cap \partial_c u(y)\}$$

*is zero.*

**Theorem.** Suppose  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  is  $C^1$  and strictly convex. Let  $\Omega \subset \mathbb{R}^n$  be an open set,  $u \in C(\Omega)$ , and  $\mathcal{B} = \{E \subset \Omega : \partial_c u(E) \text{ is Lebesgue measurable}\}$ . We have

(i) If  $K \subset \Omega$  is compact, then  $\partial_c u(K)$  is closed.

**Theorem.** Suppose  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  is  $C^1$  and strictly convex. Let  $\Omega \subset \mathbb{R}^n$  be an open set,  $u \in C(\Omega)$ , and  $\mathcal{B} = \{E \subset \Omega : \partial_c u(E) \text{ is Lebesgue measurable}\}$ . We have

(i) If  $K \subset \Omega$  is compact, then  $\partial_c u(K)$  is closed.

(ii)  $\mathcal{B}$  contains all closed subsets of  $\Omega$ .

**Theorem.** Suppose  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  is  $C^1$  and strictly convex. Let  $\Omega \subset \mathbb{R}^n$  be an open set,  $u \in C(\Omega)$ , and  $\mathcal{B} = \{E \subset \Omega : \partial_c u(E) \text{ is Lebesgue measurable}\}$ . We have

(i) If  $K \subset \Omega$  is compact, then  $\partial_c u(K)$  is closed.

(ii)  $\mathcal{B}$  contains all closed subsets of  $\Omega$ .

(iii)  $\mathcal{B}$  is a  $\sigma$ -algebra on  $\Omega$  containing all Borel subsets of  $\Omega$ . Moreover,

$$|\partial_c u(\Omega \setminus E)| = |\partial_c u(\Omega) \setminus \partial_c u(E)| \quad \forall E \in \mathcal{B}.$$

## DEFINITION OF THE MONGE-AMPÈRE MEASURE ASSOCIATED WITH $c$

Let  $g \in L^1_{\text{loc}}(\mathbb{R}^n)$  positive a.e. Suppose that  $c$  is  $C^1$  and strictly convex.

Then for each given function  $u \in C(\Omega)$ , the generalized Monge-Ampère measure of  $u$  associated with the cost function  $c$  and the weight  $g$  is the Borel measure defined by

$$\omega_c(g, u)(E) = \int_{\partial_c u(E)} g(p) dp.$$

for every Borel set  $E \subset \Omega$ . When  $g \equiv 1$ , we simply write the measure as  $\omega_c(u)$ .

Suppose that  $c$  is  $C^1$  and strictly convex, and  $c^* \in C^2(\mathbb{R}^n)$ . Then

If  $u \in C^2(\Omega)$  is  $c$ -convex in  $\Omega$ , then

$$\omega_c(g, u)(E) = \int_E g(x - Dc^*(-Du)) \det(I + D^2c^*(-Du)D^2u) dx$$

for all Borel sets  $E \subset \Omega$ .



THEREFORE THE PDE TO CONSIDER IS:

THEREFORE THE PDE TO CONSIDER IS:

$$g(x - Dc^*(-Du(x))) \det[I + D^2c^*(-Du(x))D^2u(x)] = f(x) \text{ in } \Omega,$$

THEREFORE THE PDE TO CONSIDER IS:

$$g(x - Dc^*(-Du(x))) \det[I + D^2c^*(-Du(x))D^2u(x)] = f(x) \text{ in } \Omega,$$

and the  $c$ -convex function  $u \in C(\Omega)$  is a generalized solution in the sense of Aleksandrov, or simply Aleksandrov solution, if

$$\omega_c(g, u)(E) = \int_E f(x) dx$$

for any Borel set  $E \subset \Omega$ .

If in the equation

$$g(x - Dc^*(-Du(x))) \det[I + D^2c^*(-Du(x))D^2u(x)] = f(x) \text{ in } \Omega,$$

we set  $c(x) = \frac{1}{2} |x|^2$ ,

If in the equation

$$g(x - Dc^*(-Du(x))) \det[I + D^2c^*(-Du(x))D^2u(x)] = f(x) \text{ in } \Omega,$$

we set  $c(x) = \frac{1}{2} |x|^2$ , then  $c^*(x) = \frac{1}{2} |x|^2$  and the equation becomes

$$g(x + Du(x)) \det[I + D^2u(x)] = f(x) \text{ in } \Omega,$$

that is, the Monge-Ampère equation for  $\frac{1}{2} |x|^2 + u(x)$ .

V

**MAIN RESULTS**

## COMPARISON PRINCIPLE

**Theorem.** *Let  $\Omega \subset \mathbb{R}^n$  be a bounded open set.*

## COMPARISON PRINCIPLE

**Theorem.** *Let  $\Omega \subset \mathbb{R}^n$  be a bounded open set. Let  $u, v \in C(\bar{\Omega})$  be such that  $u, v$  are  $c$ -convex on  $\Omega$ ,*

## COMPARISON PRINCIPLE

**Theorem.** *Let  $\Omega \subset \mathbb{R}^n$  be a bounded open set. Let  $u, v \in C(\bar{\Omega})$  be such that  $u, v$  are  $c$ -convex on  $\Omega$ , and  $|\partial_c u(E)| \leq |\partial_c v(E)|$  for all Borel sets  $E \subset \Omega$ .*

## COMPARISON PRINCIPLE

**Theorem.** *Let  $\Omega \subset \mathbb{R}^n$  be a bounded open set. Let  $u, v \in C(\bar{\Omega})$  be such that  $u, v$  are  $c$ -convex on  $\Omega$ , and  $|\partial_c u(E)| \leq |\partial_c v(E)|$  for all Borel sets  $E \subset \Omega$ . Assume that*

*for every open set  $D \Subset \Omega$  with  $|\partial_c v(D \setminus \text{spt}(\omega_c(u)))| = 0$ ,*

*$\exists$  a closed set  $F \subset \partial_c v(S \cap D)$  such that  $|\partial_c v(S \cap D) \setminus F| = 0$ .*

*Here  $S := \text{spt}(\omega_c(u)) \setminus \overline{\text{Int}(\text{spt}(\omega_c(u)))}$ .*

## COMPARISON PRINCIPLE

**Theorem.** *Let  $\Omega \subset \mathbb{R}^n$  be a bounded open set. Let  $u, v \in C(\bar{\Omega})$  be such that  $u, v$  are  $c$ -convex on  $\Omega$ , and  $|\partial_c u(E)| \leq |\partial_c v(E)|$  for all Borel sets  $E \subset \Omega$ . Assume that*

*for every open set  $D \Subset \Omega$  with  $|\partial_c v(D \setminus \text{spt}(\omega_c(u)))| = 0$ ,*

*$\exists$  a closed set  $F \subset \partial_c v(S \cap D)$  such that  $|\partial_c v(S \cap D) \setminus F| = 0$ .*

*Here  $S := \text{spt}(\omega_c(u)) \setminus \overline{\text{Int}(\text{spt}(\omega_c(u)))}$ . Then we have*

$$\min_{\bar{\Omega}} \{u(x) - v(x)\} = \min_{\partial\Omega} \{u(x) - v(x)\}.$$

The condition before is satisfied if any of the following hold.

1. For each  $D \Subset \Omega$  open, the set  $S \cap D$  is closed.
2. If  $\text{stp}(\omega_c(u)) = \bar{V}$  with  $V$  open subset of  $\Omega$ . In this case we have  $S = \emptyset$ .
3. If  $\omega_c(v) = \sum_{i=1}^N a_i \delta_{x_i}$ . Because in this case we have that for each  $E \subset \Omega$  there exists  $F$  compact such that  $F \subset \partial_c v(E)$  and  $|\partial_c v(E) \setminus F| = 0$ . Indeed, the set  $E \cap \{x_1, \dots, x_N\}$  is finite and  $\partial_c v(E \cap \{x_1, \dots, x_N\})$  is compact and contained in  $\partial_c v(E)$ , and  $\omega_c(v)(E) = \omega_c(v)(E \cap \{x_1, \dots, x_N\})$ , so we let  $F = \partial_c v(E \cap \{x_1, \dots, x_N\})$ .

## SOLUTION OF THE HOMOGENEOUS DIRICHLET PROBLEM

Let  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  be a continuous function. A bounded set  $E \subset \mathbb{R}^n$  is called strictly  $c$ -convex if for any  $z \in \partial E$ , any  $\delta > 0$  and any  $a > 0$ , there exist  $y, y^* \in \mathbb{R}^n$  such that

$$c(x - y) - c(z - y) \geq 0 \quad \forall x \in \partial E,$$

$$c(x - y) - c(z - y) \geq a \quad \forall x \in \partial E - B(z, \delta)$$

$$c(z - y^*) - c(x - y^*) \geq 0 \quad \forall x \in \partial E,$$

$$c(z - y^*) - c(x - y^*) \geq a \quad \forall x \in \partial E - B(z, \delta).$$

Example of a  $c$ -strictly convex set.

Example of a  $c$ -strictly convex set.

Let  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  be a convex function. Suppose that  $c(x) = l(|x|)$  for some nondecreasing function  $l : [0, \infty) \rightarrow \mathbb{R}$  satisfying  $l \in C^1(0, \infty)$  and  $\lim_{t \rightarrow +\infty} l'(t) = +\infty$ .

Example of a  $c$ -strictly convex set.

Let  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  be a convex function. Suppose that  $c(x) = l(|x|)$  for some nondecreasing function  $l : [0, \infty) \rightarrow \mathbb{R}$  satisfying  $l \in C^1(0, \infty)$  and  $\lim_{t \rightarrow +\infty} l'(t) = +\infty$ .

If  $\Omega \subset \mathbb{R}^n$  bounded open set satisfying the exterior sphere condition, then  $\Omega$  is strictly  $c$ -convex.

**Theorem.** *Suppose that  $c \in C^1(\mathbb{R}^n)$  and strictly convex.*

**Theorem.** Suppose that  $c \in C^1(\mathbb{R}^n)$  and strictly convex. Let  $\Omega \subset \mathbb{R}^n$  be a strictly  $c$ -convex open set and  $\psi : \partial\Omega \rightarrow \mathbb{R}$  be a continuous function.

**Theorem.** Suppose that  $c \in C^1(\mathbb{R}^n)$  and strictly convex. Let  $\Omega \subset \mathbb{R}^n$  be a strictly  $c$ -convex open set and  $\psi : \partial\Omega \rightarrow \mathbb{R}$  be a continuous function. Then there exists a unique  $c$ -convex function  $u \in C(\bar{\Omega})$  Aleksandrov generalized solution of the problem

$$\det[I + D^2c^*(-Du(x))D^2u(x)] = 0 \quad \text{in } \Omega,$$
$$u = \psi \quad \text{on } \partial\Omega.$$

# SOLUTION OF THE NONHOMOGENEOUS DIRICHLET PROBLEM

**Theorem.** Suppose  $c \in C^1(\mathbb{R}^n)$  is strictly convex and  $\lim_{|x| \rightarrow \infty} \frac{c(x)}{|x|} = +\infty$ .

# SOLUTION OF THE NONHOMOGENEOUS DIRICHLET PROBLEM

**Theorem.** Suppose  $c \in C^1(\mathbb{R}^n)$  is strictly convex and  $\lim_{|x| \rightarrow \infty} \frac{c(x)}{|x|} = +\infty$ . Let  $\Omega \subset \mathbb{R}^n$  be an open bounded set that is  $c$ -strictly convex.

# SOLUTION OF THE NONHOMOGENEOUS DIRICHLET PROBLEM

**Theorem.** Suppose  $c \in C^1(\mathbb{R}^n)$  is strictly convex and  $\lim_{|x| \rightarrow \infty} \frac{c(x)}{|x|} = +\infty$ . Let  $\Omega \subset \mathbb{R}^n$  be an open bounded set that is  $c$ -strictly convex. Let  $\psi \in C(\partial\Omega)$ , distinct points  $x_1, \dots, x_N \in \Omega$ , and  $a_1, \dots, a_N$  positive numbers.

# SOLUTION OF THE NONHOMOGENEOUS DIRICHLET PROBLEM

**Theorem.** Suppose  $c \in C^1(\mathbb{R}^n)$  is strictly convex and  $\lim_{|x| \rightarrow \infty} \frac{c(x)}{|x|} = +\infty$ . Let  $\Omega \subset \mathbb{R}^n$  be an open bounded set that is  $c$ -strictly convex. Let  $\psi \in C(\partial\Omega)$ , distinct points  $x_1, \dots, x_N \in \Omega$ , and  $a_1, \dots, a_N$  positive numbers.

Then there exists a unique function  $u \in C(\bar{\Omega})$ ,  $c$ -convex solution to the problem

$$\det[I + D^2c^*(-Du(x))D^2u(x)] = \sum_{i=1}^N a_i \delta_{x_i}$$
$$u = \psi, \text{ on } \partial\Omega.$$

**VI**

**IDEAS OF  
THE PROOFS**

# OUTLINE OF THE SOLUTION OF THE HOMOGENEOUS DP

Define

$$\mathcal{F} := \{f(x) = -c(x-y) - \lambda : y \in \mathbb{R}^n, \lambda \in \mathbb{R} \text{ and } f(x) \leq \psi(x) \text{ on } \partial\Omega\}.$$

$$\psi \text{ continuous on } \partial\Omega \implies \mathcal{F} \neq \emptyset$$

# OUTLINE OF THE SOLUTION OF THE HOMOGENEOUS DP

Define

$$\mathcal{F} := \{f(x) = -c(x-y) - \lambda : y \in \mathbb{R}^n, \lambda \in \mathbb{R} \text{ and } f(x) \leq \psi(x) \text{ on } \partial\Omega\}.$$

$$\psi \text{ continuous on } \partial\Omega \implies \mathcal{F} \neq \emptyset$$

Let

$$u(x) = \sup \{f(x) : f \in \mathcal{F}\}.$$

- Step 1:  $u(x) = \psi(x) \quad \forall x \in \partial\Omega.$

This follows from the  $c$ -convexity of  $\Omega$ .

- Step 1:  $u(x) = \psi(x) \quad \forall x \in \partial\Omega$ .

This follows from the  $c$ -convexity of  $\Omega$ .

- Step 2:  $u$  is  $c$ -convex and  $u \in C(\Omega)$ .

Let  $g(x) := -c(x) + \max_{\bar{\Omega}} c + \max_{\partial\Omega} \psi$ . We have  $g(x) \geq \psi(x)$  on  $\partial\Omega$ ,  $g$  is  $c$ -convex and as  $c \in C^1(\mathbb{R}^n)$  we have  $\partial_c g(\Omega) = \{0\}$  and so  $|\partial_c g(\Omega)| = 0$ . Hence for each  $f(x) = -c(x - y) - \lambda \in \mathcal{F}$ , and applying the comparison principle we get  $f(x) \leq g(x)$  in  $\bar{\Omega}$  and therefore  $u$  is uniformly bounded from above on  $\bar{\Omega}$ . Thus, we get  $u$  is uniformly bounded on  $\bar{\Omega}$ . Particularly, this implies that  $u$  is  $c$ -convex and moreover locally Lipschitz, so  $u \in C(\Omega)$ .

- Step 3:  $u$  is continuous up to the boundary.

It follows from the  $c$ -convexity of  $\Omega$  and the comparison principle.

- Step 3:  $u$  is continuous up to the boundary.

It follows from the  $c$ -convexity of  $\Omega$  and the comparison principle.

- Step 4:  $|\partial_c u(\Omega)| = 0$ .

Let  $p \in \partial_c u(\Omega)$ . Then there exists  $x_0 \in \Omega$  such that

$$u(x) \geq u(x_0) - c(x - p) + c(x_0 - p) = f(x) \quad \forall x \in \Omega.$$

There exists  $\zeta \in \partial\Omega$  satisfying  $f(\zeta) = \psi(\zeta)$ .

Then  $p \in \partial_c(u, \bar{\Omega})(x_0) \cap \partial_c(u, \bar{\Omega})(\zeta)$  but this is a set of measure zero.

# OUTLINE OF THE SOLUTION OF THE NONHOMOGENEOUS DP

- Let

$$\mathcal{H} = \{v \in C(\bar{\Omega}) : v \text{ is } c\text{-convex in } \Omega, v|_{\partial\Omega} = \psi,$$

$$|\partial_c v(\Omega)| = \sum_{i=1}^N |\partial_c v(x_i)|, \text{ and } |\partial_c v(x_i)| \leq a_i \text{ for } i = 1 \leq i \leq N\}.$$

# OUTLINE OF THE SOLUTION OF THE NONHOMOGENEOUS DP

- Let

$$\mathcal{H} = \{v \in C(\bar{\Omega}) : v \text{ is } c\text{-convex in } \Omega, v|_{\partial\Omega} = \psi,$$

$$|\partial_c v(\Omega)| = \sum_{i=1}^N |\partial_c v(x_i)|, \text{ and } |\partial_c v(x_i)| \leq a_i \text{ for } i = 1 \leq i \leq N\}.$$

Let  $W$  be the solution to  $\omega_c(W) = 0$  and  $W = \psi$  on  $\partial\Omega$ .

# OUTLINE OF THE SOLUTION OF THE NONHOMOGENEOUS DP

- Let

$$\mathcal{H} = \{v \in C(\bar{\Omega}) : v \text{ is } c\text{-convex in } \Omega, v|_{\partial\Omega} = \psi,$$

$$|\partial_c v(\Omega)| = \sum_{i=1}^N |\partial_c v(x_i)|, \text{ and } |\partial_c v(x_i)| \leq a_i \text{ for } i = 1 \leq i \leq N\}.$$

Let  $W$  be the solution to  $\omega_c(W) = 0$  and  $W = \psi$  on  $\partial\Omega$ .

We have  $W \in \mathcal{H}$ , and from the comparison principle

$$v \leq W, \text{ for each } v \in \mathcal{H}.$$

For each  $v \in \mathcal{H}$  define

$$V[v] = \int_{\Omega} (W(x) - v(x)) dx \geq 0,$$

and let

$$\beta = \sup_{v \in \mathcal{H}} V[v].$$

For each  $v \in \mathcal{H}$  define

$$V[v] = \int_{\Omega} (W(x) - v(x)) dx \geq 0,$$

and let

$$\beta = \sup_{v \in \mathcal{H}} V[v].$$

- IDEA: there exists  $u \in \mathcal{H}$  such that  $\beta = V[u]$  and  $u$  is the desired solution to the nonhomogeneous DP.

- *There exists a convex function  $w \in C(\bar{\Omega})$  with  $w = \psi$  on  $\partial\Omega$  and*

$$w(x) \leq v(x), \quad \text{in } \bar{\Omega} \text{ and for all } v \in \mathcal{H}.$$

- *There exists a convex function  $w \in C(\bar{\Omega})$  with  $w = \psi$  on  $\partial\Omega$  and*

$$w(x) \leq v(x), \quad \text{in } \bar{\Omega} \text{ and for all } v \in \mathcal{H}.$$

Assume  $\Omega$  is strictly convex, from the solution of the DP for the standard Monge-Ampère equation, there exists  $w \in C(\bar{\Omega})$  convex in  $\Omega$  solving in the weak sense

$$\begin{aligned} \det D^2 w &= \lambda_1 \delta_{x_1} + \cdots + \lambda_N \delta_{x_N} \\ w &= \psi \text{ on } \partial\Omega \end{aligned}$$

for any  $\lambda_i > 0$ ,  $i = 1, \dots, N$ . The  $\lambda_i$ 's are chosen appropriately.

We have  $\beta \leq V[w] < \infty$ . Then there exists a sequence  $\{u_n\} \subset \mathcal{H}$  such that  $V[u_n] \uparrow \beta$  as  $n \rightarrow \infty$ . From the estimates we have that

$$w(x) \leq u_n(x) \leq W(x), \quad \forall x \in \bar{\Omega}.$$

We have  $\beta \leq V[w] < \infty$ . Then there exists a sequence  $\{u_n\} \subset \mathcal{H}$  such that  $V[u_n] \uparrow \beta$  as  $n \rightarrow \infty$ . From the estimates we have that

$$w(x) \leq u_n(x) \leq W(x), \quad \forall x \in \bar{\Omega}.$$

- *There is a subsequence  $\{u_{n_k}\}$  and  $u \in C(\bar{\Omega})$  with  $u = \psi$  on  $\partial\Omega$  and  $u_{n_k} \rightarrow u$  locally uniformly in  $\Omega$  as  $k \rightarrow \infty$ .*

***$u$  IS THE SOLUTION WE LOOK FOR!***

**VII**

**FINAL REMARKS**

The second boundary value problem for the Monge-Ampère type operators arises in optimal transportation

$$g(x - Dc^*(-Du(x))) \det[I + D^2c^*(-Du(x))D^2u(x)] = f(x) \text{ in } \Omega_1$$
$$\partial_c u(\Omega_1) = \Omega_2.$$

A  $c$ -convex function  $u \in C(\Omega_1)$  is called a Brenier solution of the second BV problem if

$$\int_{\Omega_1} h(s(x))f(x)dx = \int_{\Omega_2} h(y)g(y)dy, \quad \text{for all } h \in C(\mathbb{R}^n)$$

or equivalently,

$$\int_{s^{-1}(E)} f(x)dx = \int_{E \cap \Omega_2} g(y)dy, \quad \text{for all Borel sets } E \subset \mathbb{R}^n$$

where  $s : \Omega_1 \rightarrow \mathbb{R}^n$  is a Borel measurable map defined a.e. on  $\Omega_1$  by the formula  $s(x) = x - Dc^*(-Du(x))$  whenever  $u$  is differentiable at  $x$ .

**Lemma.** . *If  $u$  is an Aleksandrov solution, then  $u$  is also a Brenier solution.*

**Lemma.** . *If  $u$  is an Aleksandrov solution, then  $u$  is also a Brenier solution.*

Conversely,

**Theorem.** *Let  $\Omega_1, \Omega_2$  be bounded domains in  $\mathbb{R}^n$  such that  $\Omega_2$  is  $c^*$ -convex relative to  $\Omega_1$ . Suppose  $u \in C(\Omega_1)$  is a  $c$ -convex function on  $\Omega_1$  Brenier solution of the second BV problem, then  $u$  is an Aleksandrov solution.*